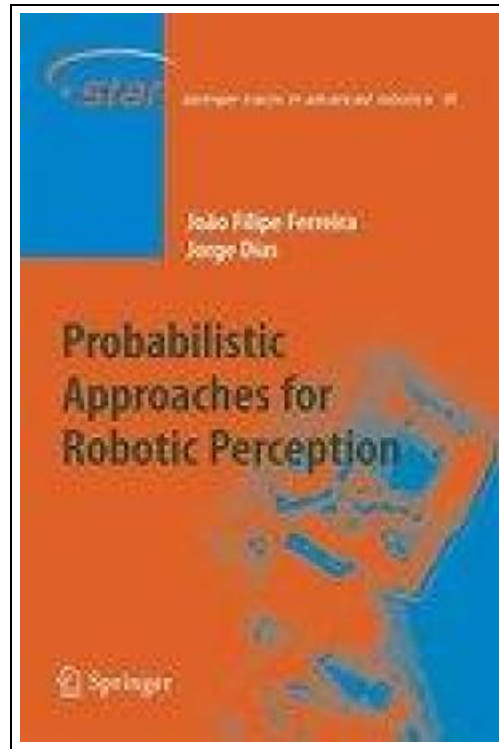


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## PROBABILISTIC APPROACHES TO ROBOTIC PERCEPTION



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